

Soc504: Inference

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Princeton

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¹Much of the material in section 2-7 is edited from Gary King's slides for Gov2000 at Harvard. Section 8 is heavily influenced by Patrick Lam.

Where We've Been and Where We're Going...

- Last Week
 - ▶ Intro and Class Overview
- This Week+
 - ▶ Theories of inference
 - ▶ Likelihood Estimation
 - ▶ Simulation
- Next Week+
 - ▶ Generalized Linear Models
- Long Run
 - ▶ likelihood $\rightarrow$ GLMs $\rightarrow$ advanced methods

Followup

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- Note that today we will be discussing things that border on philosophy. Thus it is particularly **important** that you ask questions. Often the simplest questions are the most profound!

- 1 History
- 2 Likelihood Inference
- 3 Bayesian Inference
- 4 Neyman-Pearson
- 5 Likelihood Example
- 6 Properties and Tests
- 7 Simulation
- 8 Fun With Bayes

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- While an **algorithm** tells us what to compute and provides a summary of the data, **inference** answers the question of why we are doing something (i.e. what properties it has).
- For our purposes the central question of inference will be, how do we assess the **accuracy** of an estimate?

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- Why is this hard? Well we need to calculate properties of an estimator obtained from a true distribution F even though F is **unknown**.

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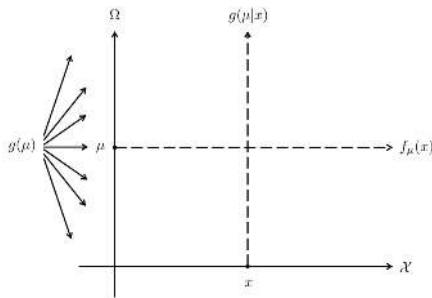


Figure 3.5 Bayesian inference proceeds vertically, given x ; frequentist inference proceeds horizontally, given μ .

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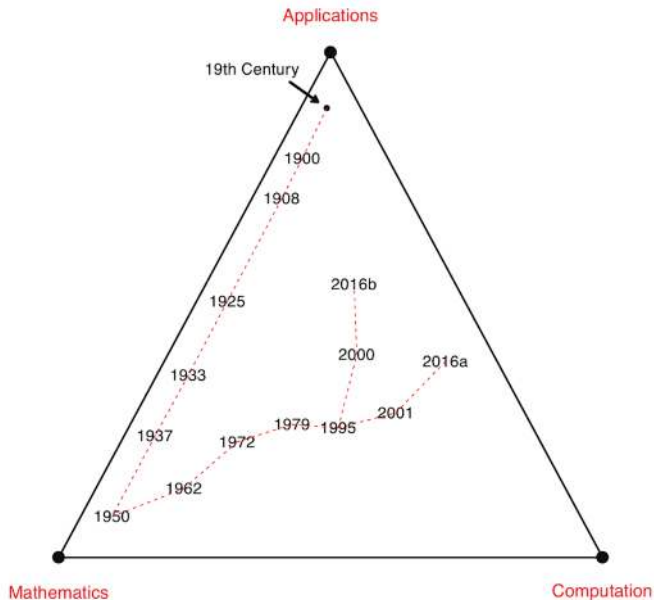
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- For those interested Stigler's "The epic story of maximum likelihood" is a fantastic account of the history of the idea.

A Perspective on a Historical Arc (Efron and Hastie 2016)



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3. A more reasonable, limited goal. Let $M = \{M^*, \theta\}$, where M^* is assumed & θ is to be estimated:

$$\mathbb{P}(\theta|y, M^*) \equiv \mathbb{P}(\theta|y)$$

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6. $L(\theta|y)$ is a function: for y fixed at the observed values, it gives the “likelihood” of any value of θ .

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- The **likelihood principle**: the data only affect inferences through the likelihood function

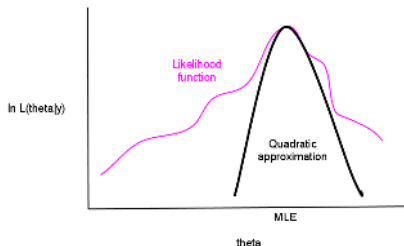
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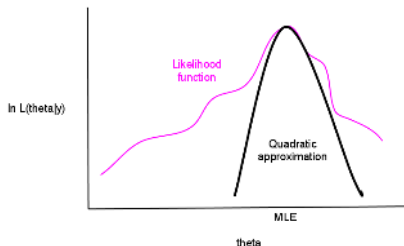
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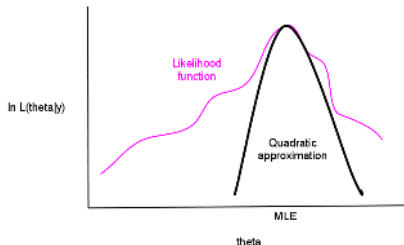
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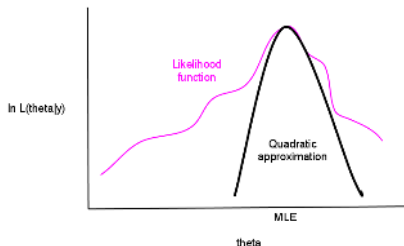
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- Uncertainty of point estimate: **curvature at the maximum**

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- Notational note: $\log$ in math is almost always used as short-hand for the natural log ($\ln$) as opposed to the base-10 log.

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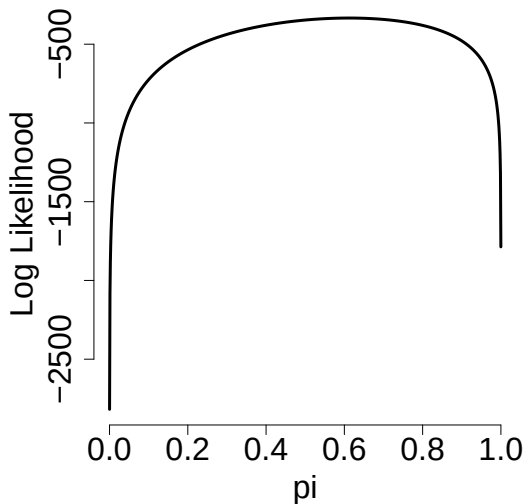
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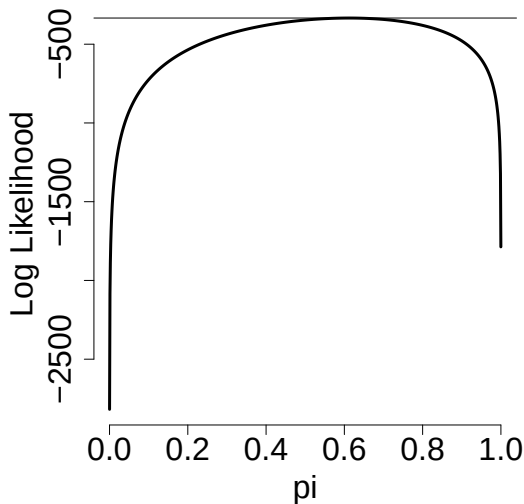
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For a fixed set of observations, what does this look like?

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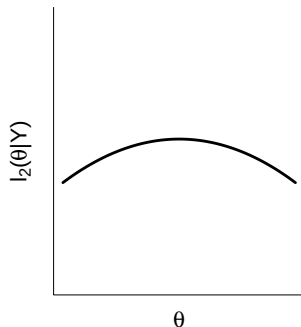
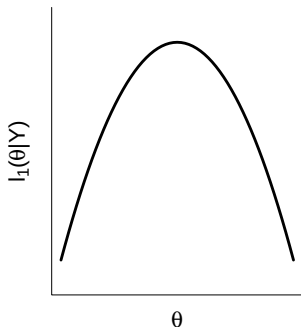
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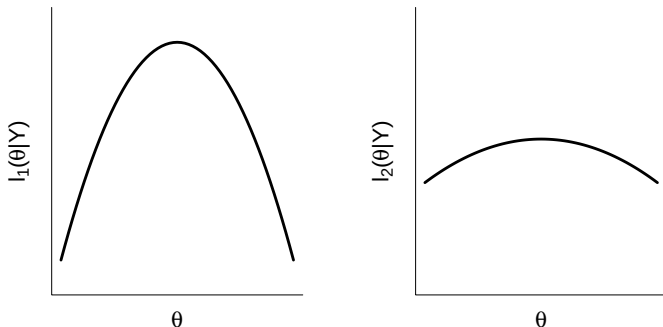
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4. A philosophical assumption that nonsample information should matter (as it always does) and be formalized and included in all inferences.

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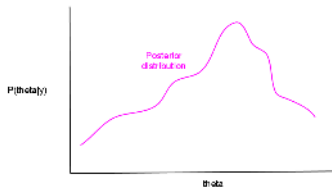
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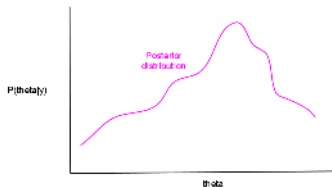
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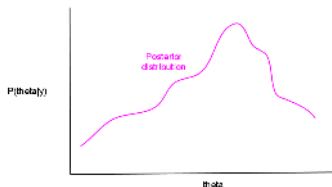


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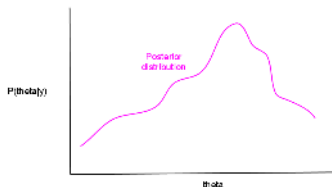
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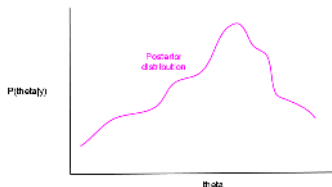
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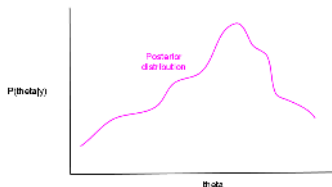
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- A perspective of growing importance is **empirical Bayes** which we will discuss later in the semester.

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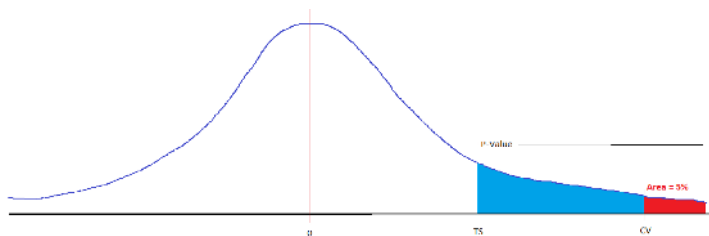
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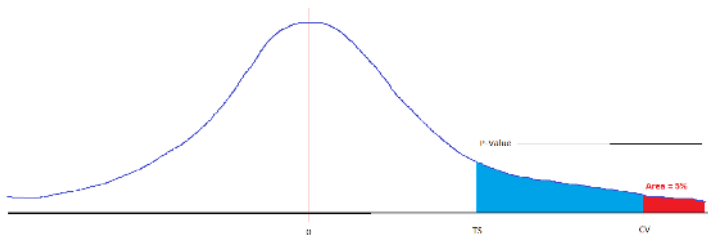


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- Is this really our quantity of interest?

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4. Methods for applied researchers: either useful or irrelevant → learn something then validate it.

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- This motivates different views of the core material such as **agnostic** and **robust** statistics.

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- What can you do with this probability density?

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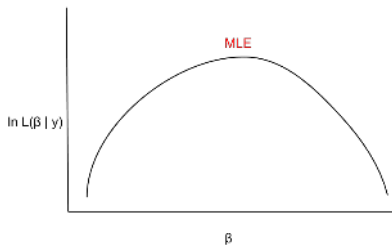
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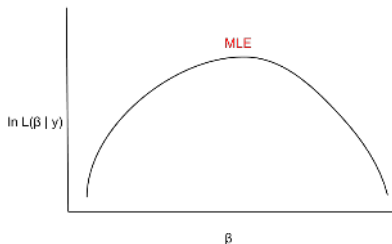
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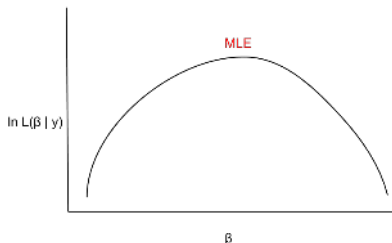


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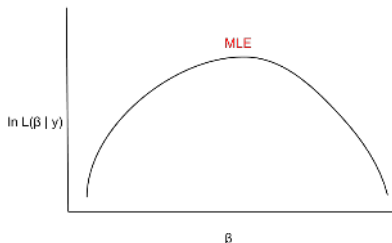
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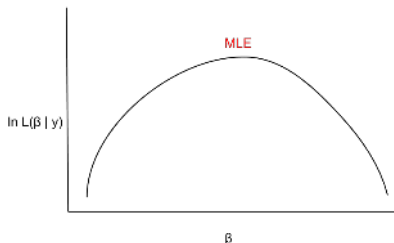
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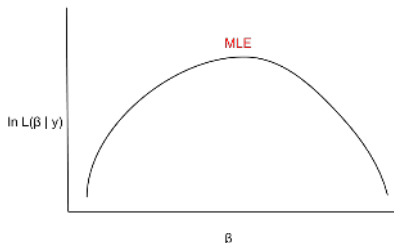
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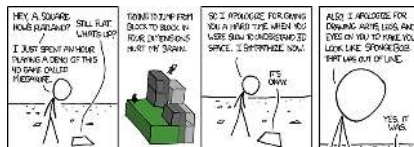
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5. No reason to summarize this curve with only the MLE

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- The problem of Flatland



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- **Graphs**



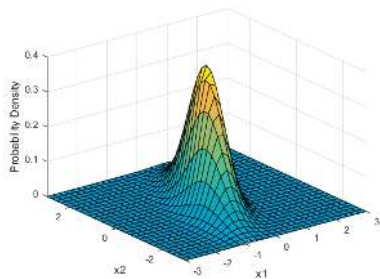
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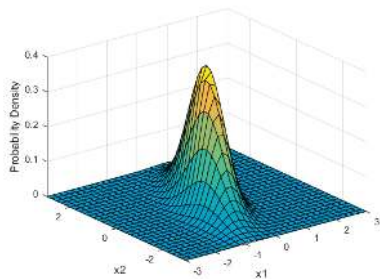
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- Maximum
- The curvature at the maximum (standard errors, about which more shortly)



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- ▶ Most commonly **gradient descent**
- ▶ Not a sharp divide- some analytic work helps numerical optimization

Example 2: Age distribution of ER visits due to wall punching

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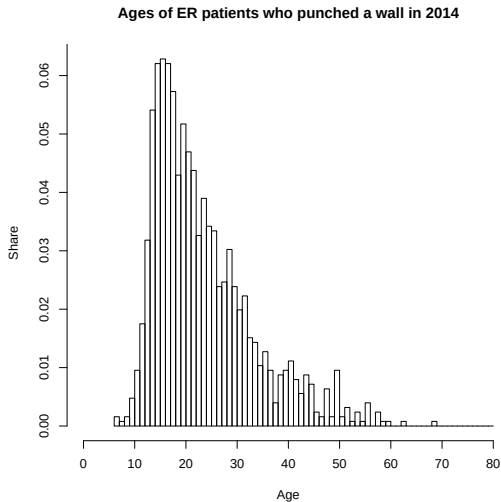
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- To do this, we write down a probability model for the data.

Empirical distribution of wall-punching ages



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The density of the log-normal distribution is given by

$$f(Y_i|\mu, \sigma^2) = \frac{1}{Y_i\sigma\sqrt{2\pi}} \exp\left(-\frac{(\ln(Y_i) - \mu)^2}{2\sigma^2}\right)$$

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Basically the same as saying $\ln(Y_i)$ is normally distributed!

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$$\mathcal{L}(\mu, \sigma^2 | \mathbf{Y}) \propto \prod_{i=1}^N f(Y_i | \mu, \sigma^2)$$

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- Now we can plug in our assumed density for Y .

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- This is why we typically work with the log-likelihood (often denoted ℓ). Because taking the log is a monotonic transformation, it retains the proportionality!

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Plotting the log-likelihood

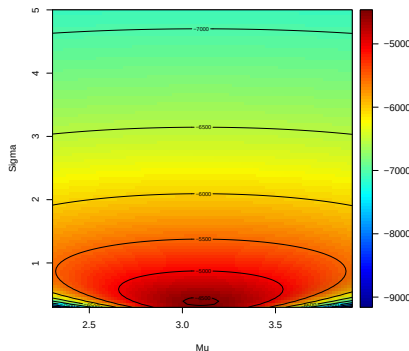


Figure: Contour plot of the log-likelihood for different values of μ and σ

Plotting the likelihood

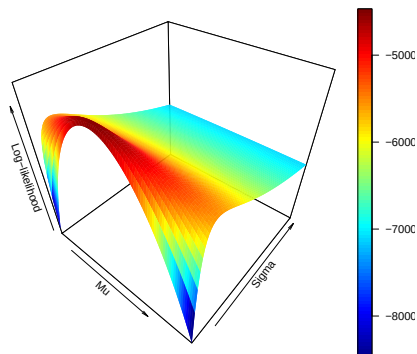


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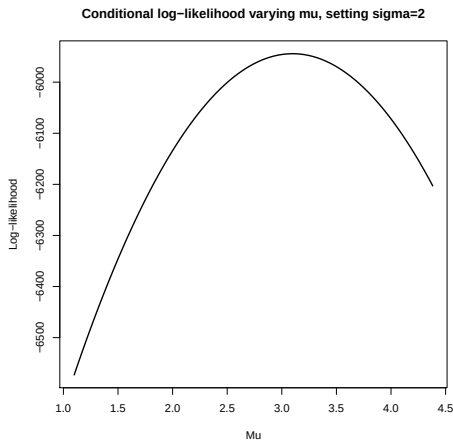


Figure: Plot of the conditional log-likelihood of μ given $\sigma = 2$

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- Let's plot the implied distribution of Y_i for each parameter set over the empirical histogram!

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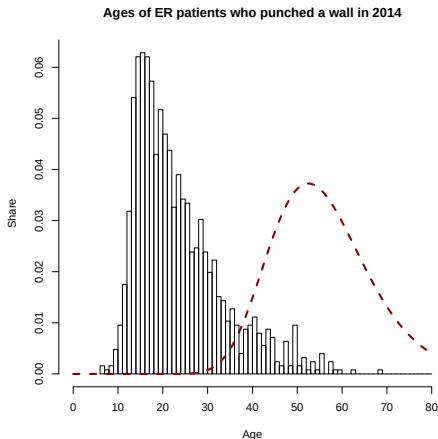


Figure: Empirical distribution of ages vs. log-normal with $\mu = 4$ and $\sigma = .2$

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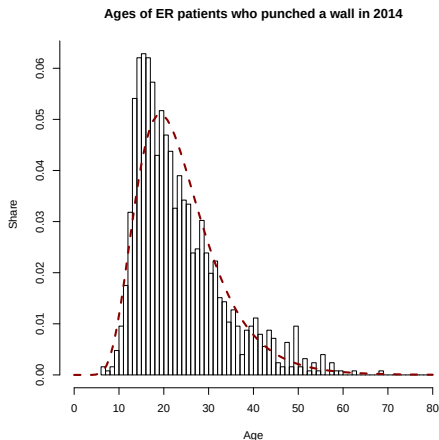


Figure: Empirical distribution of ages vs. log-normal using MLEs of parameters

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- 2 Likelihood Inference
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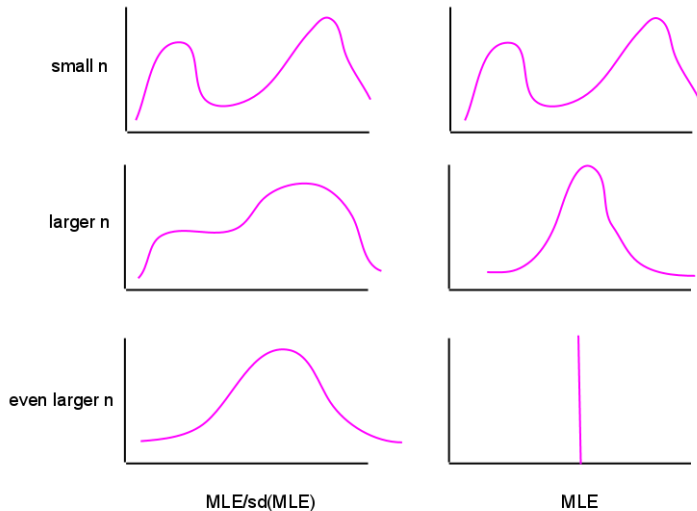
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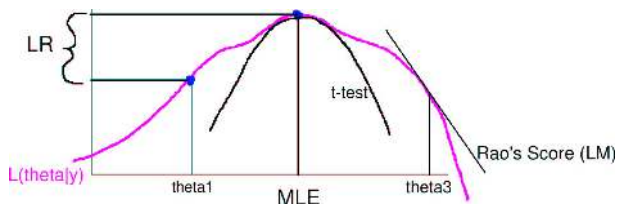
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- ③ **Asymptotic efficiency**. The MLE contains as much information as can be packed into a point estimator.

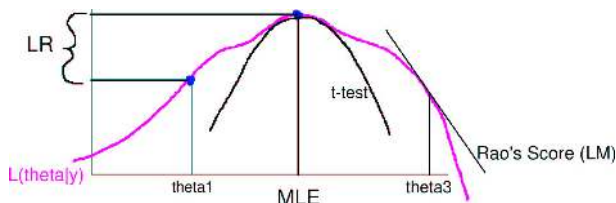
Sampling distributions of the MLE: CLT vs LLN



Uncertainty: Likelihood Ratios for nested models

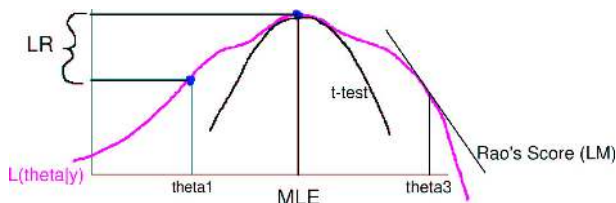


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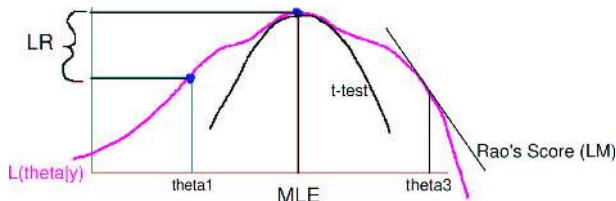
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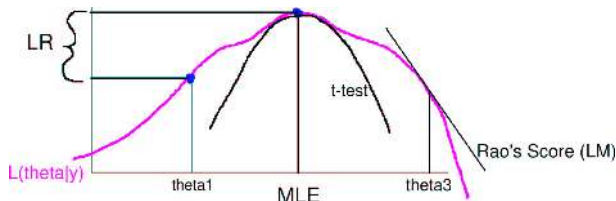
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- $\implies L^* \geq L_R^* \implies \frac{L_R^*}{L^*} \leq 1$
- This is a direct generalization of F -tests that we learned about in regression.

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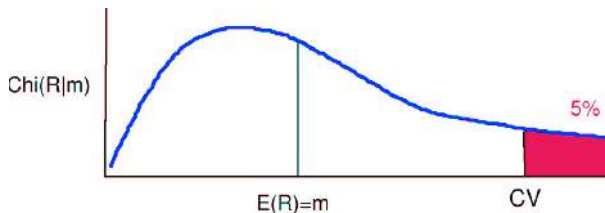
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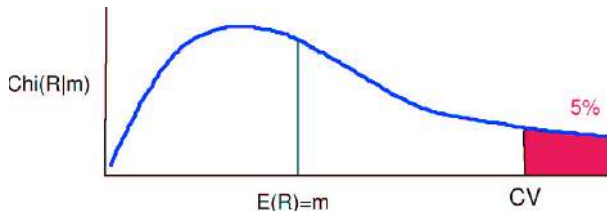
where r is the observed value of R and m is the number of restricted parameters.

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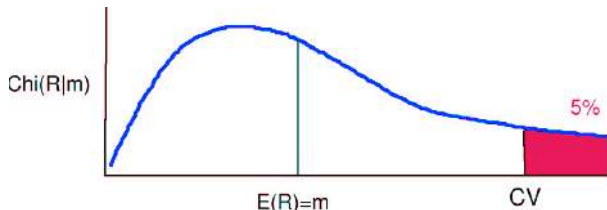


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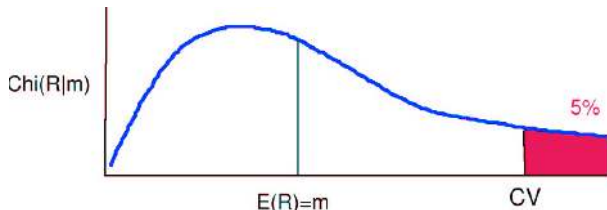
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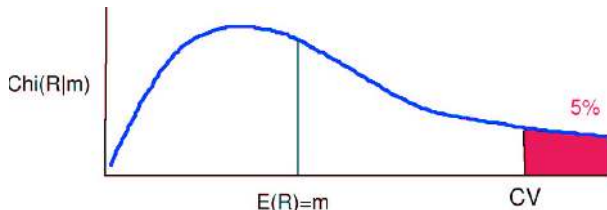
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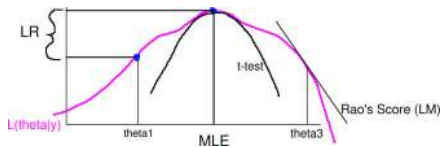
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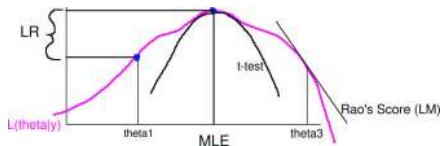
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- Thus, it might be nice to have a summary of uncertainty for every parameter separately $\leadsto$ standard errors

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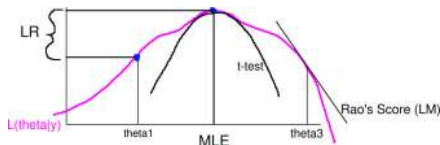


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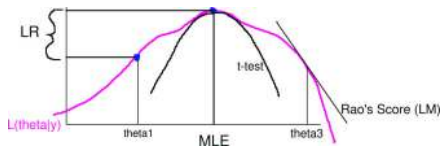
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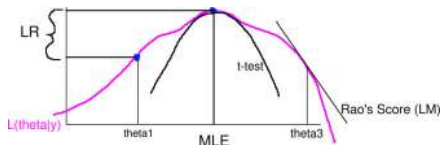
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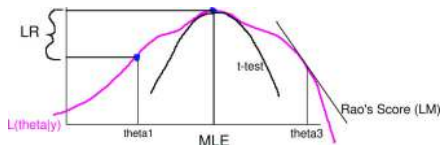
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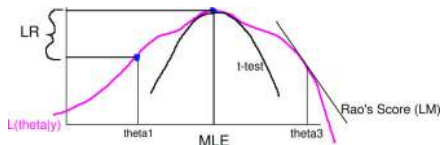
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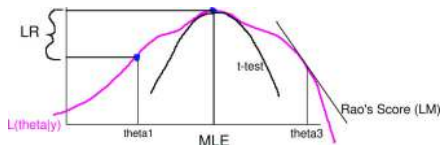
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- In certain settings we can still prove the **point estimate** is consistent and derive consistent estimators of the **sampling variance** (heteroskedasticity and serial correlation in normal model, clustering in logit and probit models, overdispersion in GLMs)

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R Code for the Log-Likelihood

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- Mathematical Form:

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  X <- as.matrix(cbind(1, X))  
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- Calling it:

```
ll.normal(c(2,1,2,1,33,4,3.2),x,y)  
ll.normal(c(2,1,2,1,33,4,3.7),x,y)  
ll.normal(c(2,1,2,1,33,4,3.5),x,y)
```

Quantities of Interest

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- Repeat Steps 1–3 $M = 1,000$ times, and plot a histogram of the results.

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 - ▶ Or, in our preferred notation, draw $\tilde{y}_{i,2016}$ from $N(X_{i,2016}\tilde{\beta}, \tilde{\sigma}^2)$

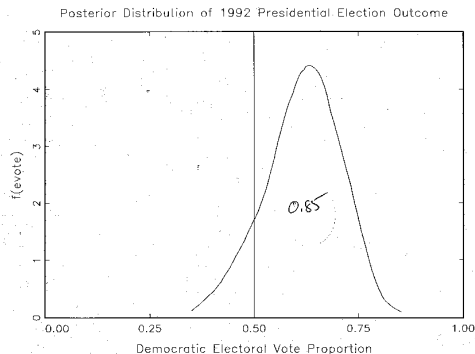
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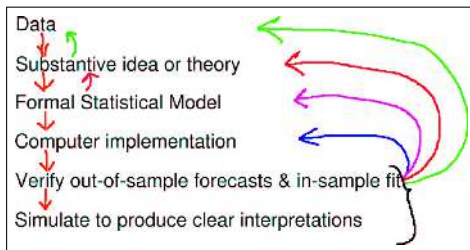
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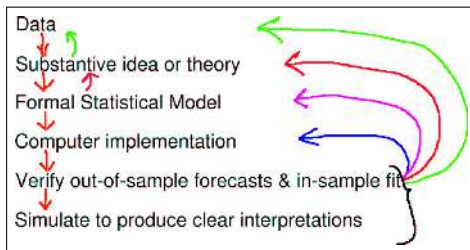
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- For what applications would this model be informative?

An Outline of the Research Process

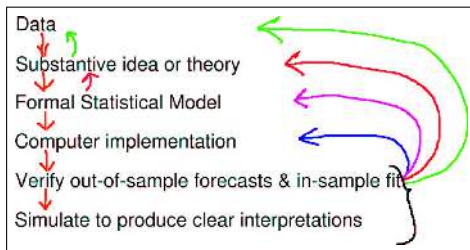


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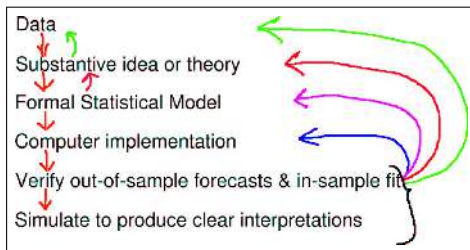
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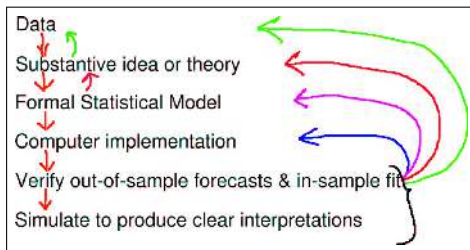
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An Outline of the Research Process



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An Outline of the Research Process



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- We will talk about this more in the last couple of weeks.

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e.g. when rolling a die, the probability of a 3 or 5 is just $\frac{1}{6} + \frac{1}{6}$

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- ▶ “objective”, dominant paradigm in statistics, and cheerleaders incl Fischer.

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- ▶ example: our prior over a coin's outcomes (Bernoulli process) might be $p = \frac{1}{2}$ or $p = \frac{1}{3}$ or $p = 1$ ('degenerate')— we can then conduct our trials (the tosses themselves). Alternatively, we might have a prior on the value of some $\hat{\beta}$ in a regression.

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There is a fixed, true value of θ , and we maximize the likelihood to estimate θ and make assumptions to generate uncertainty about our estimate of θ .

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NB: *Bayesian is too hard. Why use it?*

B: Bayesian methods allow us to easily estimate models that are too hard to estimate (cannot computationally find the MLE) or unidentified (no unique MLE exists) with non-Bayesian methods. Bayesian methods also allow us to incorporate prior/qualitative information into the model.

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There is a Bayesian way to do any non-Bayesian parametric model.

A Simple (Beta-Binomial) Model: The Canonical Example

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with $n = 82$.

Assumptions:

- Each flip is a Bernoulli trial.
- The coin has the same probability of landing heads each flip .
- The outcomes are independent.

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*Bayesian **priors** are just adding pseudo observations to the data.*

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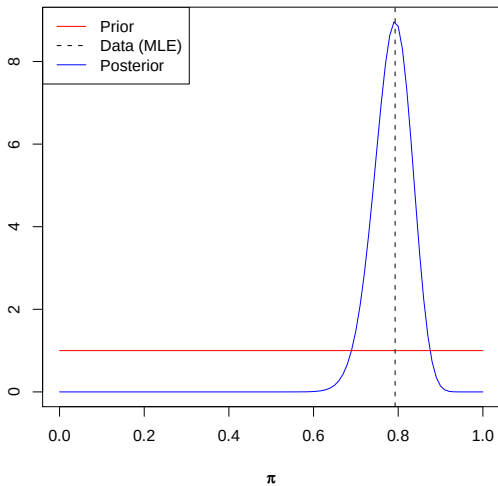
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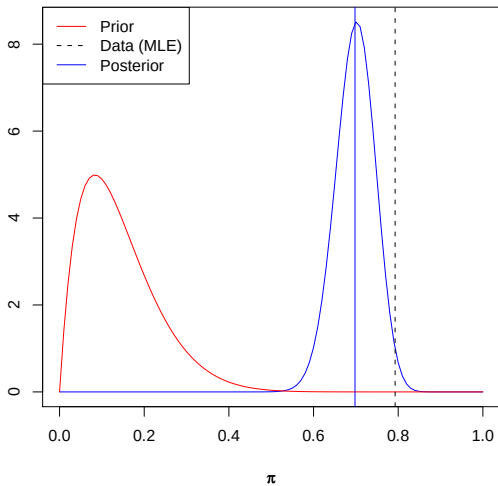
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Big Point: Bayesian inference necessitates the estimation of **distributions** rather than parameters

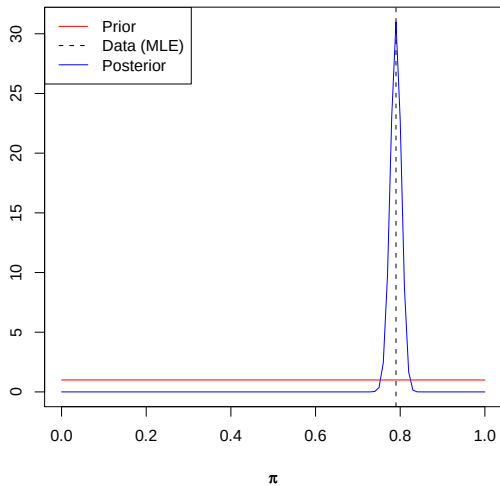
Uninformative Beta(1,1) Prior



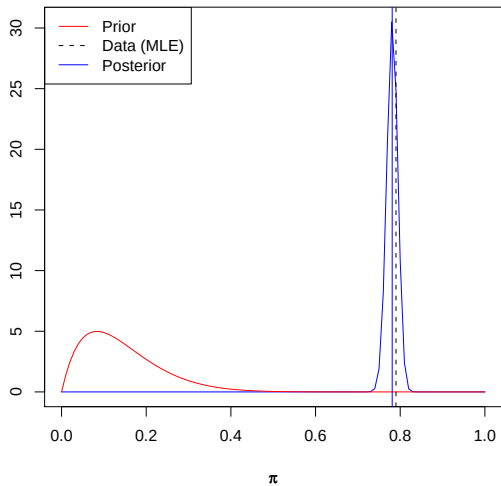
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Uninformative Beta(1,1) Prior (n=1000)



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Conjugate models are great because we can find the exact **posterior**, but...

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$$p(\alpha, \beta, \theta, \sigma, \pi, \tau | Y) \propto \prod_{k=1}^K \prod_{s=1}^S \frac{\exp(-\frac{\alpha_{ks}}{1/4})}{1/4} \times \frac{\Gamma(\sum_{w=1}^W \lambda_w)}{\prod_{w=1}^W \Gamma(\lambda_w)} \prod_{w=1}^W \theta_{k,w}^{\lambda_w-1} \times$$
$$\prod_{i=1}^n \prod_{t=2005}^{2007} \prod_{s=1}^S \left[\beta_s \frac{\Gamma(\sum_{k=1}^K \alpha_{ks})}{\prod_{k=1}^K \Gamma(\alpha_{ks})} \prod_{k=1}^K \pi_{itk}^{\alpha_{ks}-1} \prod_{j=1}^{D_{it}} \prod_{k=1}^K \left[\pi_{itk} \prod_{w=1}^W \theta_{kw}^{y_{ijtw}} \right]^{\tau_{ijtk}} \right]^{\sigma_{its}}$$

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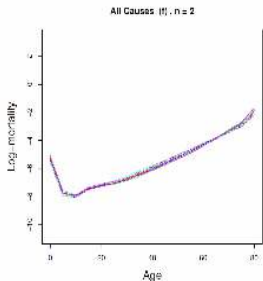
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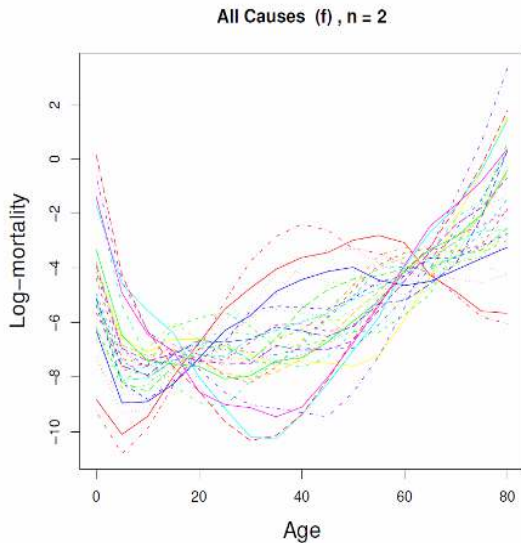
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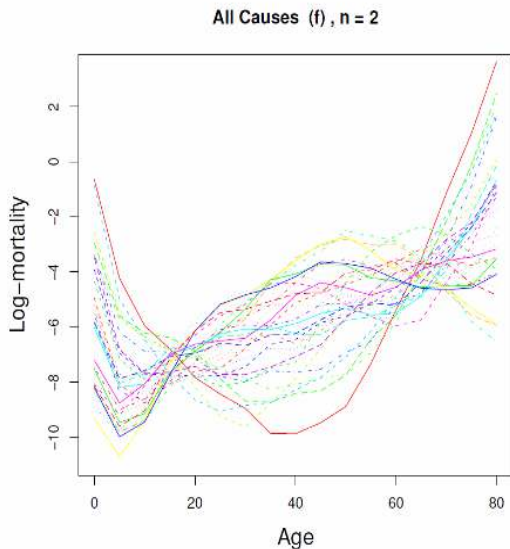
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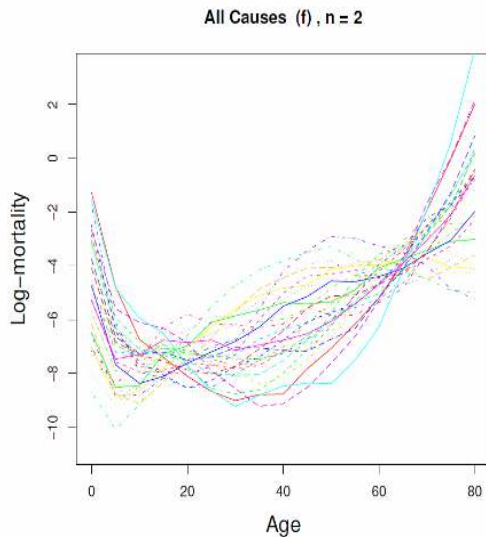
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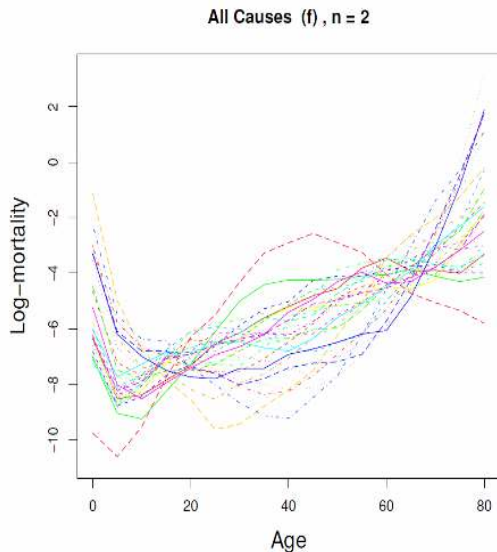
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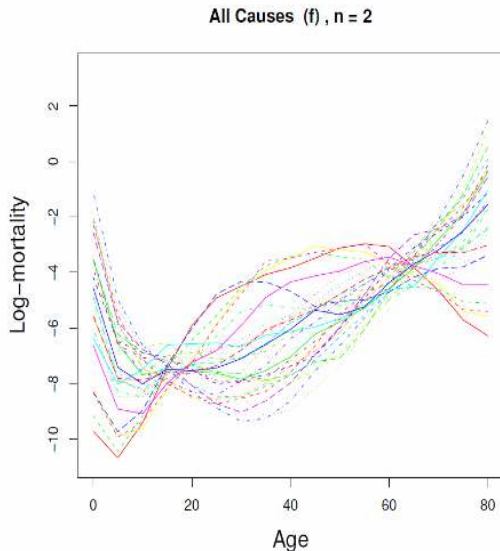
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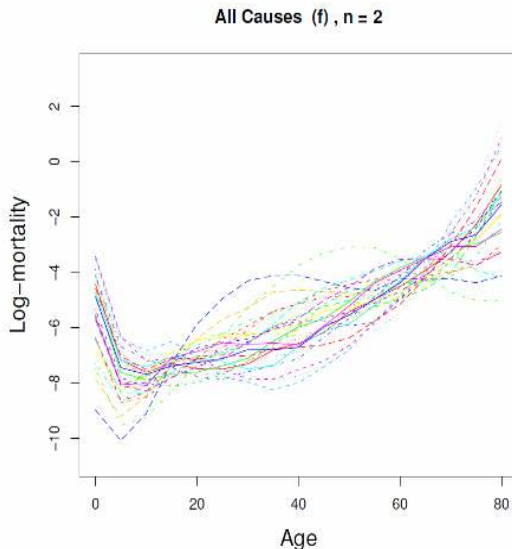
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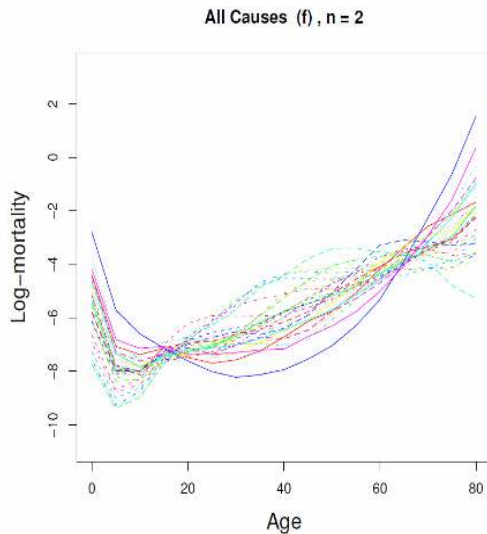
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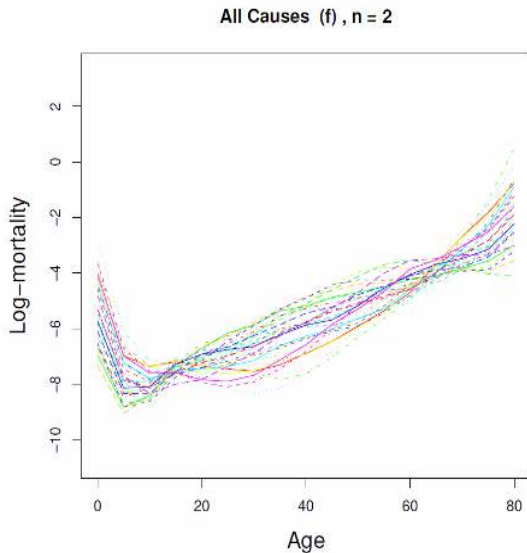
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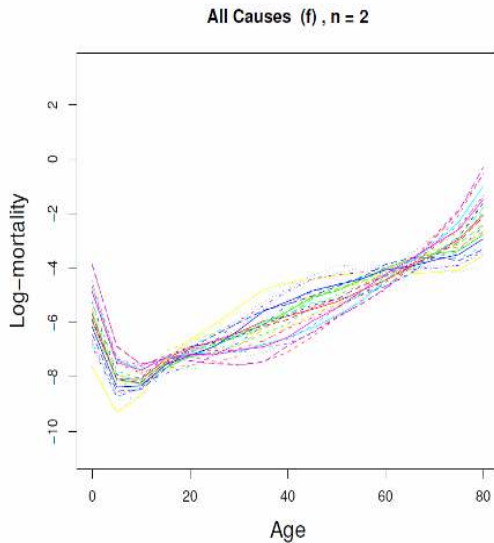
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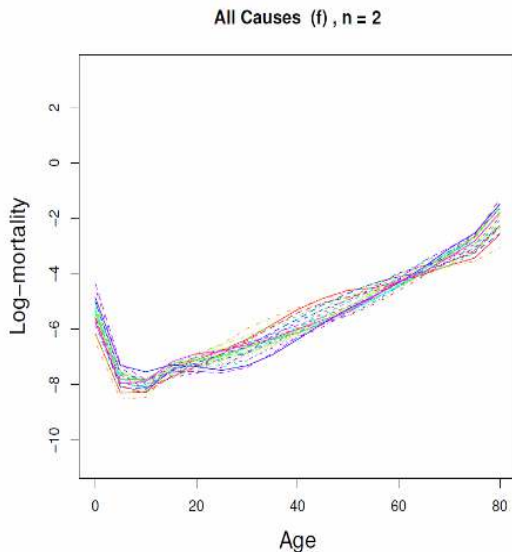
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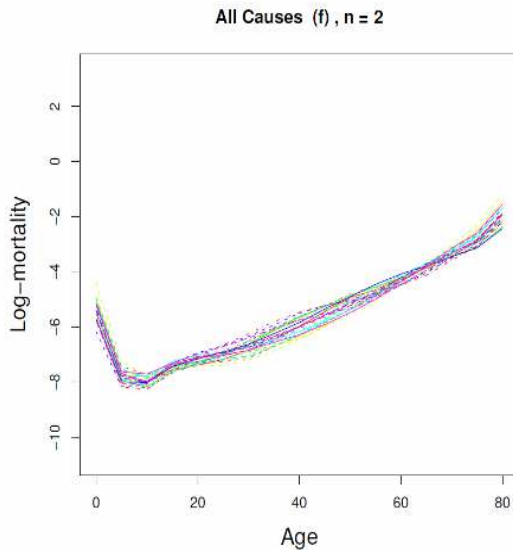
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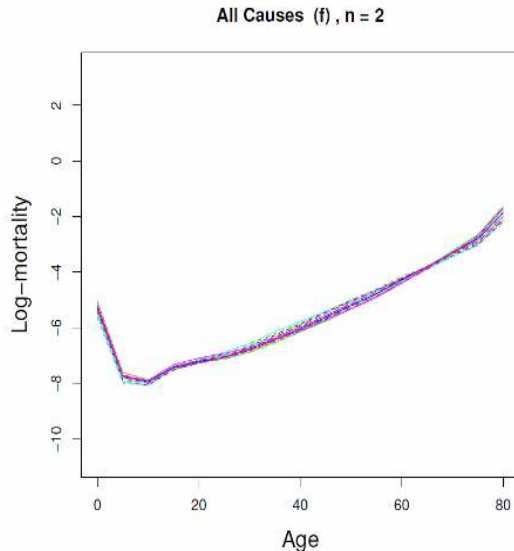
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All solved using Bayesian Hierarchical Models! (See *Demographic Forecasting* and the *YourCast* package.